## CMOS Programmable Timer High Voltage Types (20V Rating)

## Features

- Low Symmetrical Output Resistance, Typically $100 \Omega$ at $V_{D D}=15 \mathrm{~V}$
- Built-In Low-Power RC Oscillator
- Oscillator Frequency Range $\qquad$ DC to 100 kHz
- External Clock (Applied to Pin 3) can be Used Instead of Oscillator
- Operates as $2^{\mathrm{N}}$ Frequency Divider or as a SingleTransition Timer
- $\mathbf{Q} / \overline{\mathbf{Q}}$ Select Provides Output Logic Level Flexibility
- AUTO or MASTER RESET Disables Oscillator During Reset to Reduce Power Dissipation
- Operates With Very Slow Clock Rise and Fall Times
- Capable of Driving Six Low Power TTL Loads, Three Low-Power Schottky Loads, or Six HTL Loads Over the Rated Temperature Range
- Symmetrical Output Characteristics
- 100\% Tested for Quiescent Current at 20V
- 5V, 10V, and 15V Parametric Ratings
- Meets All Requirements of JEDEC Standard No. 13B, "Standard Specifications for Description of 'B' Series CMOS Devices"


## Description

CD4541B programmable timer consists of a 16-stage binary counter, an oscillator that is controlled by external R-C components (2 resistors and a capacitor), an automatic power-on reset circuit, and output control logic. The counter increments on positive-edge clock transitions and can also be reset via the MASTER RESET input.

## Pinout

CD4541B
(CERDIP, PDIP, SOIC, SOP, TSSOP)


The output from this timer is the Q or $\overline{\mathrm{Q}}$ output from the 8th, 10th, 13th, or 16th counter stage. The desired stage is chosen using time-select inputs A and B (see Frequency Select Table).
The output is available in either of two modes selectable via the MODE input, pin 10 (see Truth Table). When this MODE input is a logic "1", the output will be a continuous square wave having a frequency equal to the oscillator frequency divided by $2^{N}$. With the MODE input set to logic "0" and after a MASTER RESET is initiated, the output (assuming Q output has been selected) changes from a low to a high state after $2^{\mathrm{N}-1}$ counts and remains in that state until another MASTER RESET pulse is applied or the MODE input is set to a logic " 1 ".
Timing is initialized by setting the AUTO RESET input (pin 5) to logic " 0 " and turning power on. If pin 5 is set to logic " 1 ", the AUTO RESET circuit is disabled and counting will not start until after a positive MASTER RESET pulse is applied and returns to a low level. The AUTO RESET consumes an appreciable amount of power and should not be used if low-power operation is desired. For reliable automatic power-on reset, $\mathrm{V}_{\mathrm{DD}}$ should be greater than 5 V .
The RC oscillator, shown in Figure 2, oscillates with a frequency determined by the RC network and is calculated using:
$\mathrm{f}=\frac{1}{2.3 \mathrm{R}_{\mathrm{TC}} \mathrm{C}_{\mathrm{TC}}}$
Where f is between 1 kHz and 100 kHz and $R_{S} \geq 10 \mathrm{k} \Omega$ and $\approx 2 R_{T C}$

## Ordering Information

| PART NUMBER | TEMP. RANGE <br> $\left({ }^{\circ} \mathbf{C}\right)$ | PACKAGE |
| :--- | :---: | :--- |
| CD4541BF3A | -55 to 125 | 14 Ld CERDIP |
| CD4541BE | -55 to 125 | 14 Ld PDIP |
| CD4541BM | -55 to 125 | 14 Ld SOIC |
| CD4541BMT | -55 to 125 | 14 Ld SOIC |
| CD4541BM96 | -55 to 125 | 14 Ld SOIC |
| CD4541BNSR | -55 to 125 | 14 Ld SOP |
| CD4541BPW | -55 to 125 | 14 Ld TSSOP |
| CD4541BPWR | -55 to 125 | 14 Ld TSSOP |

NOTE: When ordering, use the entire part number. The suffixes 96 and $R$ denote tape and reel. The suffix $T$ denotes a small-quantity reel of 250 .

## Functional Diagram



FIGURE 1.
FREQUENCY SELECTION TABLE

| A | B | NO. OF <br> STAGES N | COUNT 2 $^{\mathbf{N}}$ |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 13 | 8192 |
| 0 | 1 | 10 | 1024 |
| 1 | 0 | 8 | 256 |
| 1 | 1 | 16 | 65536 |

TRUTH TABLE

| PIN | STATE |  |
| :---: | :--- | :--- |
|  | $\mathbf{0}$ | $\mathbf{1}$ |
| 5 | Auto Reset On | Auto Reset Disable |
| 6 | Master Reset Off | Master Reset On |
| 9 | Output Initially Low After <br> Reset (Q) | Output Initially High After <br> Reset ( $\overline{\mathrm{Q}})$ |
| 10 | Single Transition Mode | Recycle Mode |



FIGURE 2. RC OSCILLATOR CIRCUIT

## Absolute Maximum Ratings

DC Supply - Voltage Range, $\mathrm{V}_{\mathrm{DD}}$
Voltages Referenced to $\mathrm{V}_{\text {SS }}$ Terminal ........... -0.5 V to +20 V
Input Voltage Range, All Inputs ................ -0.5 V to $\mathrm{V}_{\mathrm{DD}}+0.5 \mathrm{~V}$
DC Input Current, Any One Input . . . . . . . . . . . . . . . . . . . . . $\pm 10 \mathrm{~mA}$
Device Dissipation Per Output Transistor
For $\mathrm{T}_{\mathrm{A}}=$ Full Package Temperature Range
(All Package Types)
100 mW

## Operating Conditions

Temperature Range $\mathrm{T}_{\mathrm{A}}$
$-55^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$
Supply Voltage Range
For $\mathrm{T}_{\mathrm{A}}=$ Full Package Temperature Range . . . . . 3V (Min), 18V (Typ)

## Thermal Information

Package Thermal Impedance, $\theta_{\mathrm{JA}}$ (see Note 1)

| PDIP package | $80^{\circ} \mathrm{C} / \mathrm{W}$ |
| :---: | :---: |
| SOIC package | $86^{\circ} \mathrm{C} / \mathrm{W}$ |
| SOP package | $76^{\circ} \mathrm{C} / \mathrm{W}$ |
| TSSOP package | $113^{\circ} \mathrm{C} / \mathrm{W}$ |
| Maximum Junction Temperature (Plastic Package) | . $150^{\circ} \mathrm{C}$ |
| Maximum Storage Temperature Range (TSTG) | $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ |
| Maximum Lead Temperature (Soldering 10s) |  |
| At Distance $1 / 16$ in $\pm 1 / 32$ in ( $1.59 \mathrm{~mm} \pm 0.79 \mathrm{~mm}$ ) from case for 10s Maximum . . . . . . . . . . . . . . . . (SOIC - Lead Tips Only) | $\ldots 265^{\circ} \mathrm{C}$ |

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTE:

1. The package thermal impedance is calculated in accordance with JESD 51-7.

## Electrical Specifications

| PARAMETER | CONDITIONS |  |  | LIMITS AT INDICATED TEMPERATURES ( ${ }^{\circ} \mathrm{C}$ ) |  |  |  |  |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & \mathrm{V}_{\mathrm{O}} \\ & \text { (V) } \end{aligned}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}} \\ & (\mathrm{~V}) \end{aligned}$ | $V_{D D}$ <br> (V) | -55 | -40 | 85 | 125 | 25 |  |  |  |
|  |  |  |  |  |  |  |  | MIN | TYP | MAX |  |
| Quiescent Device Current, (Note 2) IDD (Max) | - | 0, 5 | 5 | 5 | 5 | 150 | 150 | - | 0.04 | 5 | $\mu \mathrm{A}$ |
|  | - | 0, 10 | 10 | 10 | 10 | 300 | 300 | - | 0.04 | 10 | $\mu \mathrm{A}$ |
|  | - | 0,15 | 15 | 20 | 20 | 600 | 600 | - | 0.04 | 20 | $\mu \mathrm{A}$ |
|  | - | 0,20 | 20 | 100 | 100 | 3000 | 3000 | - | 0.08 | 100 | $\mu \mathrm{A}$ |
| Output Low (Sink) Current loL (Min) | 0.4 | 0, 5 | 5 | 1.9 | 1.85 | 1.26 | 1.08 | 1.55 | 3.1 | - | mA |
|  | 0.5 | 0, 10 | 10 | 5 | 4.8 | 3.3 | 2.8 | 4 | 8 | - | mA |
|  | 1.5 | 0, 15 | 15 | 12.6 | 12 | 8.4 | 7.2 | 10 | 20 | - | mA |
| Output High (Source) <br> Current, IOH (Min) | 4.6 | 0, 5 | 5 | -1.9 | -1.85 | -1.26 | -1.08 | -1.55 | -3.1 | - | mA |
|  | 2.5 | 0, 5 | 5 | -6.2 | -6 | -4.1 | -3 | -5 | -10 | - | mA |
|  | 9.5 | 0, 10 | 10 | -5 | -4.8 | -3.3 | -2.8 | -4 | -8 | - | mA |
|  | 13.5 | 0, 15 | 15 | -12.6 | -12 | -8.4 | -7.2 | -10 | -20 | - | mA |
| Output Voltage: <br> Low-Level, VOL (Max) | - | 0, 5 | 5 | - | 0.05 |  |  | - | 0 | 0.05 | V |
|  | - | 0, 10 | 10 | - | 0.05 |  |  | - | 0 | 0.05 | V |
|  | - | 0,15 | 15 | - | 0.05 |  |  | - | 0 | 0.05 | V |
| Output Voltage: <br> High-Level, $\mathrm{V}_{\mathrm{OH}}$ (Min) | - | 0, 5 | 5 | - | 4.95 |  |  | 4.95 | 5 | - | V |
|  | - | 0, 10 | 10 | - | 9.95 |  |  | 9.95 | 10 | - | V |
|  | - | 0, 15 | 15 | - | 14.95 |  |  | 14.95 | 15 | - | V |
| Input Low Voltage, $\mathrm{V}_{\mathrm{IL}}$ (Max) | 0.5, 4.5 | - | 5 | - | 1.5 |  |  | - | - | 1.5 | V |
|  | 1,9 | - | 10 | - | 3 |  |  | - | - | 3 | V |
|  | 1.5, 13.5 | - | 15 | - | 4 |  |  | - | - | 4 | V |

Electrical Specifications (Continued)

| PARAMETER | CONDITIONS |  |  | LIMITS AT INDICATED TEMPERATURES ( ${ }^{\circ} \mathrm{C}$ ) |  |  |  |  |  |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $V_{0}$ <br> (V) | $\mathrm{V}_{\text {IN }}$ <br> (V) | $V_{D D}$ <br> (V) | -55 | -40 | 85 | 125 | 25 |  |  |  |
|  |  |  |  |  |  |  |  | MIN | TYP | MAX |  |
| Input High Voltage, $\mathrm{V}_{\mathrm{IH}}$ (Min) | 0.5, 4.5 | - | 5 | - |  | 3.5 |  | 3.5 | - | - | V |
|  | 1, 9 | - | 10 | - |  | 7 |  | 7 | - | - | V |
|  | 1.5, 13.5 | - | 15 | - |  | 11 |  | 11 | - | - | V |
| Input Current, ${ }_{\text {IN }}$ (Max) | - | 0,18 | 18 | $\pm 0.1$ | $\pm 0.1$ | $\pm 1$ | $\pm 1$ | - | $\pm 10^{-5}$ | $\pm 0.1$ | $\mu \mathrm{A}$ |

NOTE:
2. With AUTO RESET enabled, additional current drain at $25^{\circ} \mathrm{C}$ is:
$7 \mu \mathrm{~A}$ (Typ), $200 \mu \mathrm{~A}$ (Max) at 5 V ;
$30 \mu \mathrm{~A}$ (Typ), $350 \mu \mathrm{~A}$ (Max) at 10 V ;
$80 \mu \mathrm{~A}$ (Typ), $500 \mu \mathrm{~A}$ (Max) at 15 V

Dynamic Electrical Specifications $T_{A}=25^{\circ} \mathrm{C}$, Input $\mathrm{t}_{\mathrm{r}}, \mathrm{t}_{\mathrm{f}}=20 \mathrm{~ns}, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=200 \mathrm{k} \Omega$

| PARAMETER | SYMBOL | $\mathrm{V}_{\text {DD }}(\mathrm{V})$ | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Propagation Delay Times Clock to Q | $\left(2^{8}\right) t_{\text {PHL }}, t_{\text {PLH }}$ | 5 | - | 3.5 | 10.5 | $\mu \mathrm{s}$ |
|  |  | 10 | - | 1.25 | 3.8 | $\mu \mathrm{s}$ |
|  |  | 15 | - | 0.9 | 2.9 | $\mu \mathrm{s}$ |
|  | $\left(2^{16}\right) t_{\text {PHL }}, t_{\text {PLH }}$ | 5 | - | 6.0 | 18 | $\mu \mathrm{s}$ |
|  |  | 10 | - | 3.5 | 10 | $\mu \mathrm{s}$ |
|  |  | 15 | - | 2.5 | 7.5 | $\mu \mathrm{s}$ |
| Transition Time | ${ }^{\text {T }}$ HL | 5 | - | 100 | 200 | ns |
|  |  | 10 | - | 50 | 100 | ns |
|  |  | 15 | - | 40 | 80 | ns |
|  | ${ }_{\text {T }}{ }_{\text {HL }}$ | 5 | - | 180 | 360 | ns |
|  |  | 10 | - | 90 | 180 | ns |
|  |  | 15 | - | 65 | 130 | ns |
| MASTER RESET, CLOCK Pulse Width |  | 5 | 900 | 300 | - | ns |
|  |  | 10 | 300 | 100 | - | ns |
|  |  | 15 | 225 | 85 | - | ns |
| Maximum Clock Pulse Input Frequency | ${ }^{\mathrm{f}} \mathrm{CL}$ | 5 | - | 1.5 | - | MHz |
|  |  | 10 | - | 4 | - | MHz |
|  |  | 15 | - | 6 | - | MHz |
| Maximum Clock Pulse Input Rise or Fall time | $t_{r}, t_{f}$ | 5,10,15 | Unlimited |  |  | $\mu \mathrm{s}$ |

## CD4541B

## Digital Timer Application

A positive pulse on MASTER RESET resets the counters and latch. The output goes high and remains high until the number of pulses, selected by A and B, are counted. This circuit is retriggerable and is as accurate as the input frequency. If additional accuracy is desired, an external clock can be used on pin 3. A setup time equal to the width of the one-shot output is required immediately following initial power up, during which time the output will be high.


FIGURE 3. DIGITAL TIMER APPLICATION CIRCUIT


| DIM PINS ** | 14 | 16 | 18 | 20 |
| :---: | :---: | :---: | :---: | :---: |
| A | 0.300 <br> $(7,62)$ <br> BSC | 0.300 <br> $(7,62)$ <br> BSC | 0.300 <br> $(7,62)$ <br> BSC | 0.300 <br> $(7,62)$ <br> BSC |
| B MAX | 0.785 <br> $(19,94)$ | .840 <br> $(21,34)$ | 0.960 <br> $(24,38)$ | 1.060 <br> $(26,92)$ |
| B MIN | - | - | - | - |
| C MAX | 0.300 <br> $(7,62)$ | 0.300 <br> $(7,62)$ | 0.310 <br> $(7,87)$ | 0.300 <br> $(7,62)$ |
| C MIN | 0.245 <br> $(6,22)$ | 0.245 <br> $(6,22)$ | 0.220 <br> $(5,59)$ | 0.245 <br> $(6,22)$ |



NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. This package is hermetically sealed with a ceramic lid using glass frit.
D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
E. Falls within MIL STD 1835 GDIP1-T14, GDIP1-T16, GDIP1-T18 and GDIP1-T20.


NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Falls within JEDEC MS-001, except 18 and 20 pin minimum body Irngth (Dim A). D. The 20 pin end lead shoulder width is a vendor option, either half or full width.

D (R-PDSO-G**)
8 PINS SHOWN


| PIMS | 8 | 14 | 16 |
| :---: | :---: | :---: | :---: |
| A MAX | 0.197 <br> $(5,00)$ | 0.344 <br> $(8,75)$ | 0.394 <br> $(10,00)$ |
|  | 0.189 | 0.337 | 0.386 |
|  | $(4,80)$ | $(8,55)$ | $(9,80)$ |

NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed $0.006(0,15)$.
D. Falls within JEDEC MS-012

NS (R-PDSO-G**)
14-PINS SHOWN


| DIM PINS ** | 14 | 16 | 20 | 24 |
| :---: | :---: | :---: | :---: | :---: |
| A MAX | 10,50 | 10,50 | 12,90 | 15,30 |
| A MIN | 9,90 | 9,90 | 12,30 | 14,70 |

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed 0,15.


| DIM | PINS ** | $\mathbf{8}$ | $\mathbf{1 4}$ | $\mathbf{1 6}$ | $\mathbf{2 0}$ | $\mathbf{2 4}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A MAX | 3,10 | 5,10 | 5,10 | 6,60 | 7,90 | 9,80 |
| A MIN | 2,90 | 4,90 | 4,90 | 6,40 | 7,70 | 9,60 |

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15 .
D. Falls within JEDEC MO-153

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